

Diagonalization of Linear Operator

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Announcement

- 明天 (5/5, 週四) 助教會來講解作業二
- 會有 bonus 的作業

Review

$$P = [p_1 \quad \cdots \quad p_n]$$

eigenvector

$$D = \begin{bmatrix} d_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & d_n \end{bmatrix}$$

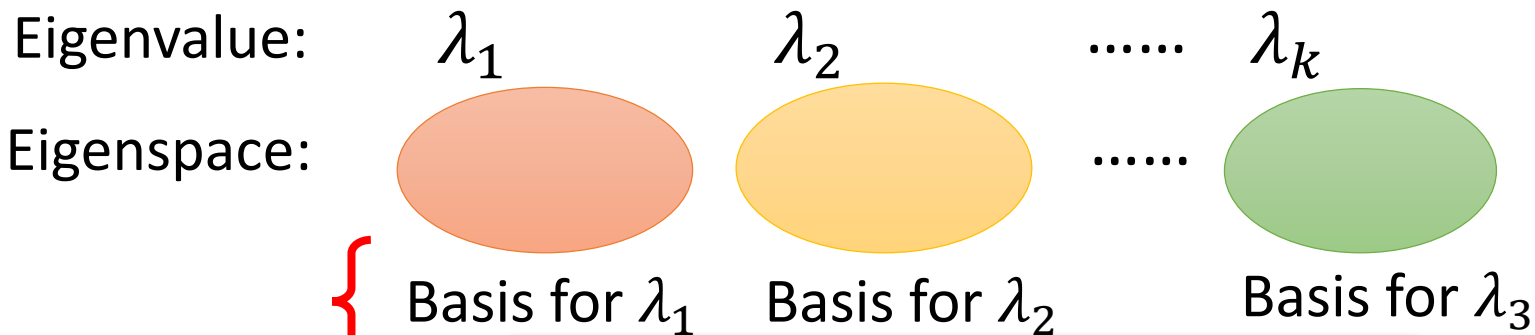
eigenvalue

An $n \times n$ matrix A is diagonalizable ($A = PDP^{-1}$)

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The eigenvectors of A can form a basis for \mathbb{R}^n .

$$\det(A - tI_n) = (t - \lambda_1)^{m_1} (t - \lambda_2)^{m_2} \cdots (t - \lambda_k)^{m_k} (\dots)$$



Independent Eigenvectors

Diagonalization of Linear Operator

• Example 1: $T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} 8x_1 + 9x_2 \\ -6x_1 - 7x_2 \\ 3x_1 + 3x_2 - x_3 \end{bmatrix}$

The standard matrix is $A = \begin{bmatrix} 8 & 9 & 0 \\ -6 & -7 & 0 \\ 3 & 3 & -1 \end{bmatrix}$

\Rightarrow the characteristic polynomial is $-(t + 1)^2(t - 2)$

Eigenvalue -1:

$$\mathcal{B}_1 = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Eigenvalue 2:

$$\mathcal{B}_2 = \left\{ \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix} \right\}$$

$\Rightarrow \mathcal{B}_1 \cup \mathcal{B}_2$ is a basis of \mathcal{R}^3

Diagonalization of Linear Operator

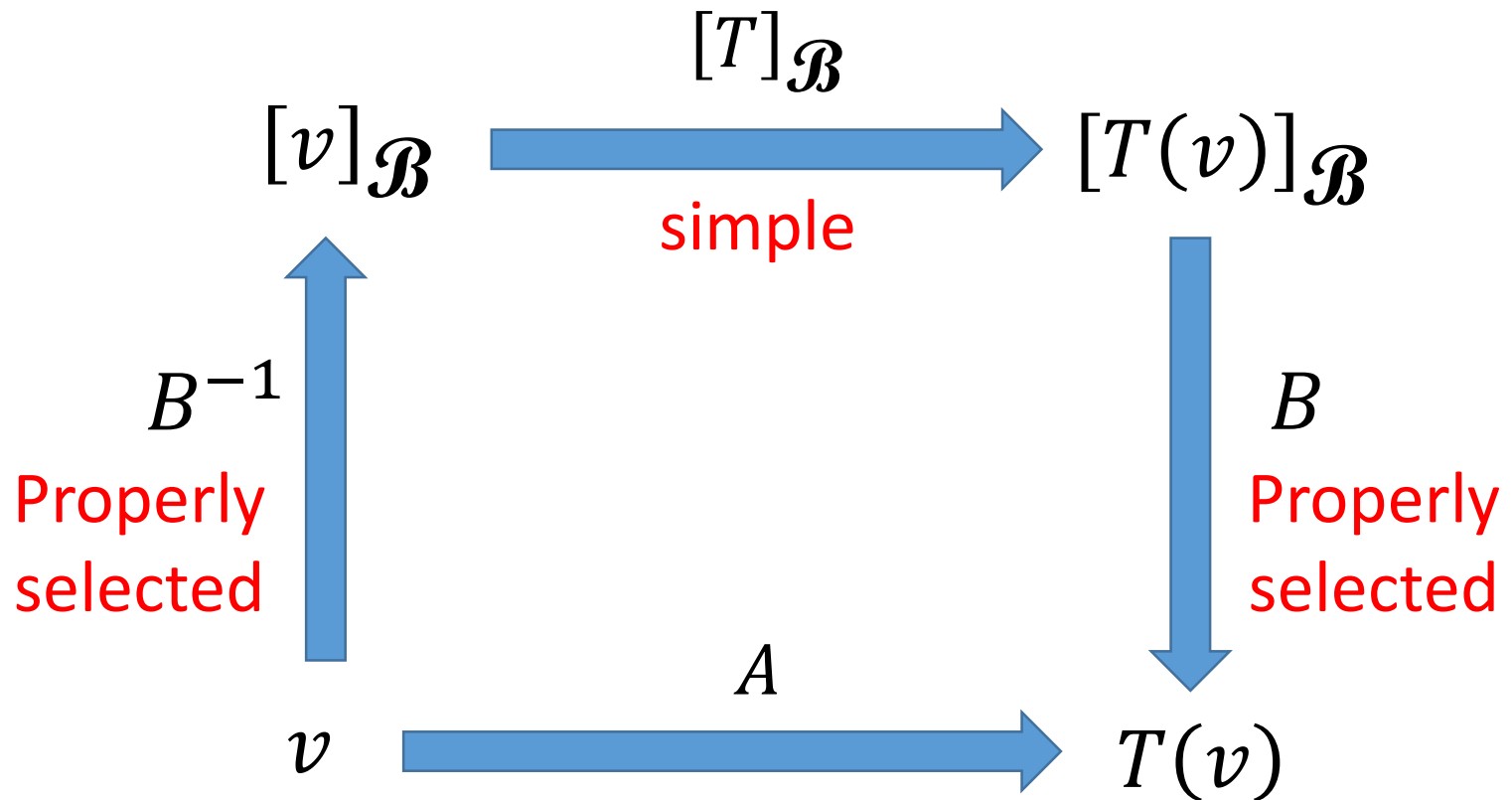
• Example 2: $T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} -x_1 + x_2 + 2x_3 \\ x_1 - x_2 \\ 0 \end{bmatrix}$

The standard matrix is $A = \begin{bmatrix} -1 & -t & 1 & 2 \\ 1 & -1 & -t & 0 \\ 0 & 0 & 0 & -t \end{bmatrix}$

$$\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

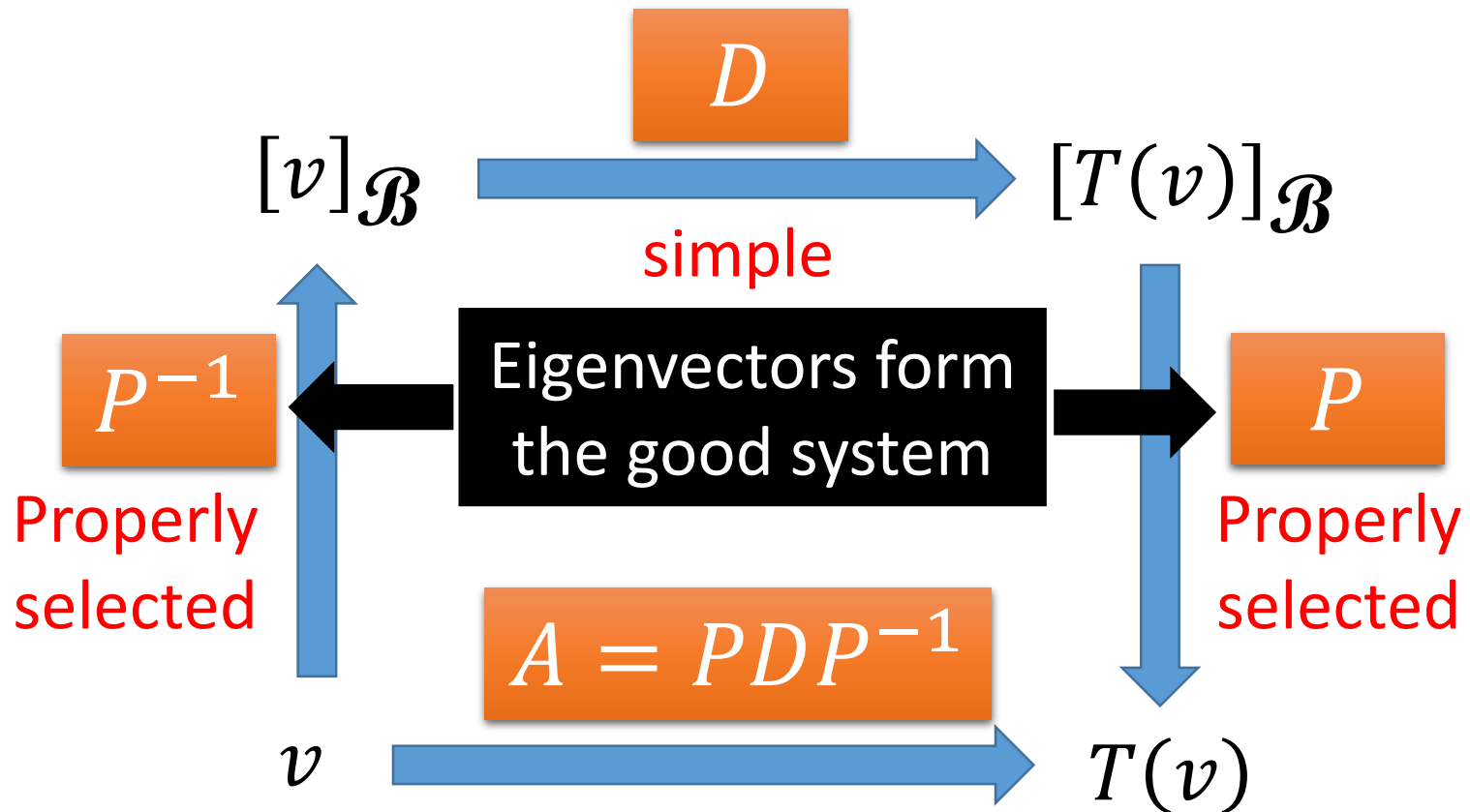
This lecture

- Reference: Chapter 5.4



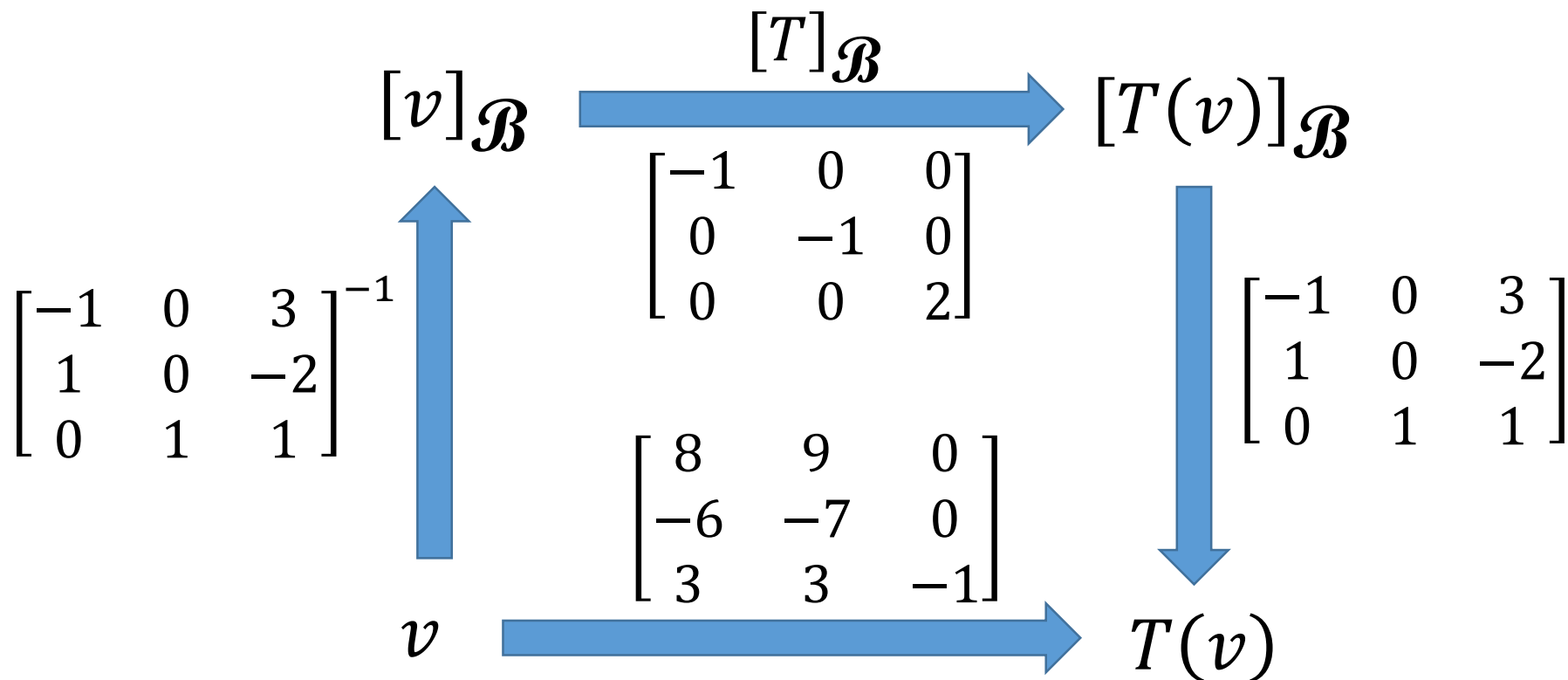
Diagonalization of Linear Operator

- If a linear operator T is diagonalizable



Diagonalization of Linear Operator

$$T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} 8x_1 + 9x_2 \\ -6x_1 - 7x_2 \\ 3x_1 + 3x_2 - x_3 \end{bmatrix} \quad \begin{matrix} -1: \\ \mathcal{B}_1 = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \end{matrix} \quad \begin{matrix} 2: \\ \mathcal{B}_2 = \left\{ \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix} \right\} \end{matrix}$$



Another Application of Eigenvector: Page Rank

- Reference:
 - THE \$25,000,000,000 EIGENVECTOR: THE LINEAR ALGEBRA BEHIND GOOGLE
 - <http://userpages.umbc.edu/~kogan/teaching/m430/GooglePageRank.pdf>
 - A SURVEY OF EIGENVECTOR METHODS FOR WEB INFORMATION RETRIEVAL
 - <http://doradca.oeiizk.waw.pl/survey.pdf>